

BTeV Tracking System

Pixel Vertex Detector (WBS 1.2) Straw Tracker (WBS 1.6)

Silicon Tracker (WBS 1.7)

Simon Kwan (WBS 1.2)

Alan Hahn (WBS 1.6)

Luigi Moroni (WBS 1.7)



Overview

Brief description of the BTeV tracking system

- > Pixel vertex detector
- > Forward tracker (Straw & Silicon strips)

Details of each sub-system

- > Project requirements & Description
- Project organization
- > Cost, Schedule, and Critical path
- > Milestones
- ➤ Risk Assessment
- ➤ Responses to DOE CD-1 recommendations

Presentations prepared for the breakout sessions

- Conclusion
- Glossary



Introduction

Requirements

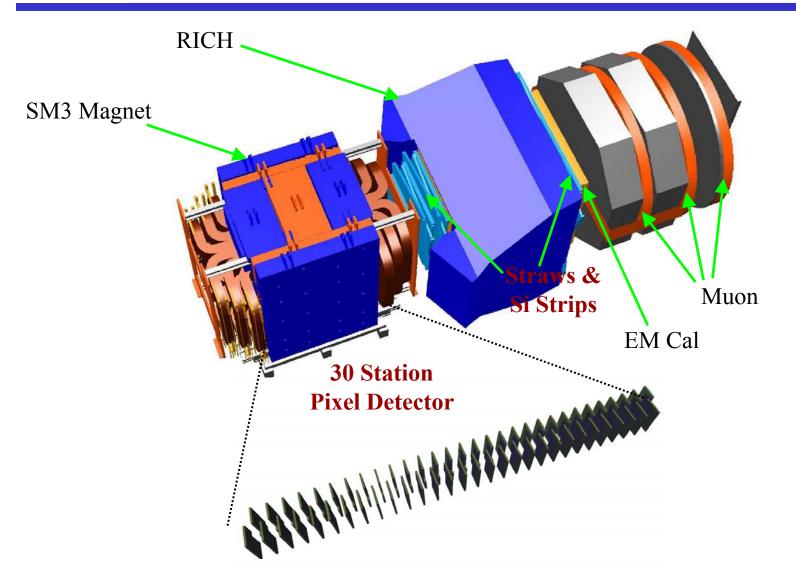
- Coverage:
 - > Aperture 300 mr
 - ➤ Momentum acceptance 3 >100 GeV/c
- Tracking efficiency > 98%
- Resolution for vertex detector:
 - \triangleright Spatial : < 9 µm
 - \triangleright Time: < 50 fs
- Vertex detector info available for use in L1 trigger
- Angular resolution:
 - > Better than 0.1 mr
- Momentum resolution:
 - > 1% at 100 GeV/c
- Can handle huge data rate and survive high radiation dosage

Key features

- Vertex Detector
 - Pixel Detector (WBS1.2)
 - Precise vertex detection and reasonable momentum measurement capability
 - Fast info available for use in L1 vertex trigger
- Forward Tracker
 - > Straw (WBS1.6) and Silicon Strip (WBS1.7)
 - Precise momentum measurement, Ks/Λ detection, project tracks into RICH, EMCAL, Muon chambers
 - Combination of Silicon strips near the beam and Straw Chambers at large radius



BTeV Detector





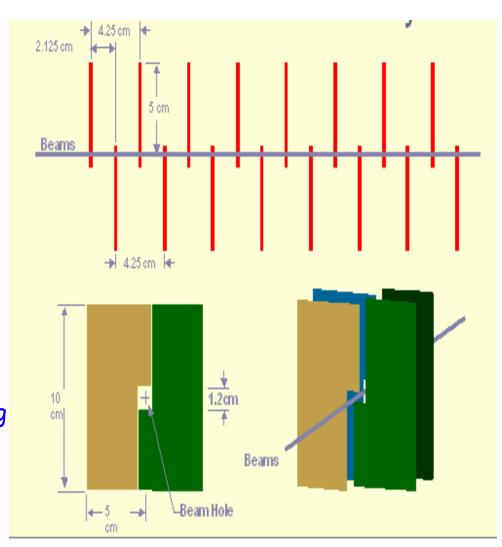
Technical Description of Pixel Detector WBS1.2

Reasons for Pixel Detector:

- Superior signal to noise
- Radiation Hard
- Excellent spatial resolution:
- $<9 \mu m$ for all tracks
- Pattern recognition power
- Very low occupancy

Special features:

- Info used directly in the L1 trigger
- Placed inside a dipole and gives standalone momentum measurement
- Sitting close to beam and be retractable during beam refill -> needs vacuum system and rf shielding
- 30 stations with 23 million pixels in total
- Total length ~1.3m



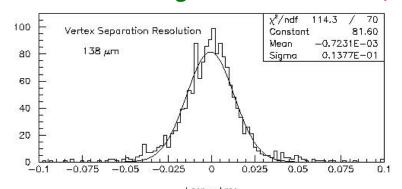


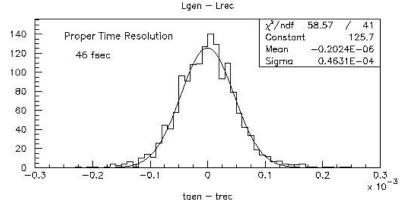
Pixel Detector Properties & Performance WBS1.2

Property	Value
Pixel Size	50 μm x 400 μm
Outer plane dimension	10 cm x 10 cm
Central square hole (adjustable)	Nominal setting: 12 mm x 12 mm
Number of planes	60
Number of stations	30
Number of pixels	23 million
Total Silicon active area	0.5 m ²
Separation of stations	4.25 cm

$$B_s \to D_s K^+$$

Primary-secondary vertex separation Reconst - generated. $\sigma = 138\mu$





 τ_{proper} (reconstructed) - τ_{proper} (generated) $\sigma = 46 \text{ fsec}$



- WBS 1.2.1: Sensor & Detector Hybridization
 - Includes design, procurement and testing of sensor wafers, flip-chip mating of sensors to readout chips to get pixel modules
- WBS 1.2.2: Electronics
 - ➤ Includes pixel readout chips, data cables, PIFC, Feed-through Board (FTB), HV/LV power supplies and cables
- WBS 1.2.3: Mechanical & Vacuum system
 - Includes substrate, fixtures, vacuum vessel, position control system, cooling system, vacuum system, support structure, and rf shield
- WBS 1.2.4: System Integration
 - ➤ Includes production HDI, pixel module assembly and testing, teststands, station assembly, detector assembly, beam test, control &monitoring, fast interlocks, system test, system software
- WBS 1.2.5: Project Management

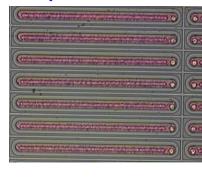


Pixel Detector

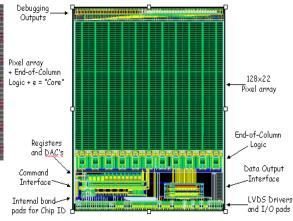
WBS 1.2

- Pixel Sensor bump-bonded to Readout chip
- Fine segmentation
 - > 50 µm x 400 µm
 - ➤ Large number of channels
 - Electronics in the active tracking volume
 - ➤ High power density (~ 3kW
 - -> cooling system)
- Basic building block Multichip Module (MCM)
 - ➤ 4 types (4, 5, 6, and 8 chip array)
 - Large number of HDI and flex cables
- Assemble modules on both sides of substrate to form pixel half plane; an x-measuring half-plane and a ymeasuring half-plane form a halfstation

Si pixel sensors

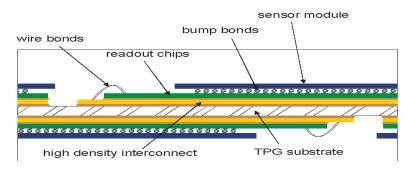


Pixel Readout chip



Multichip module

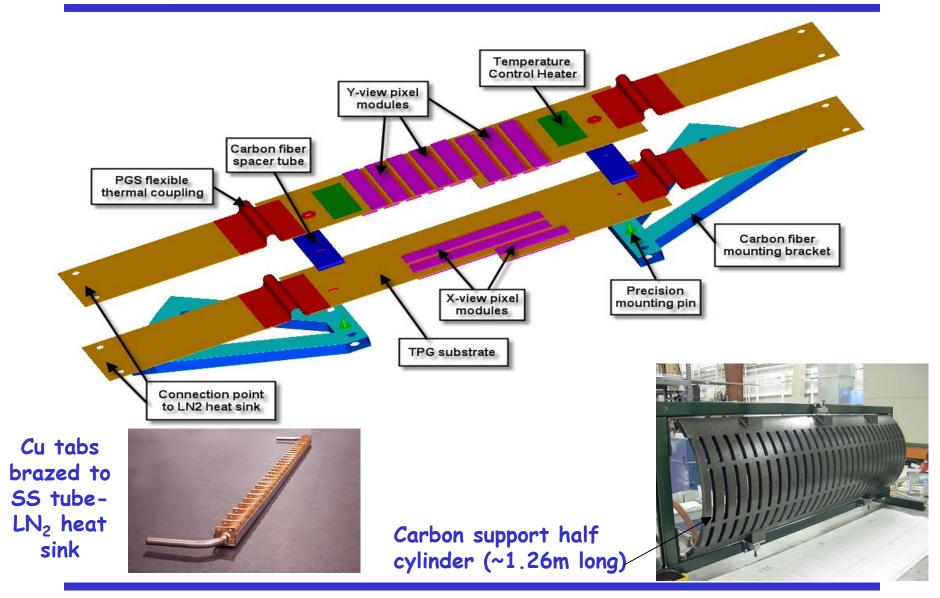






Pixel Half-Station

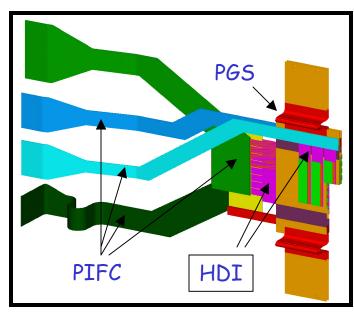
WBS1.2



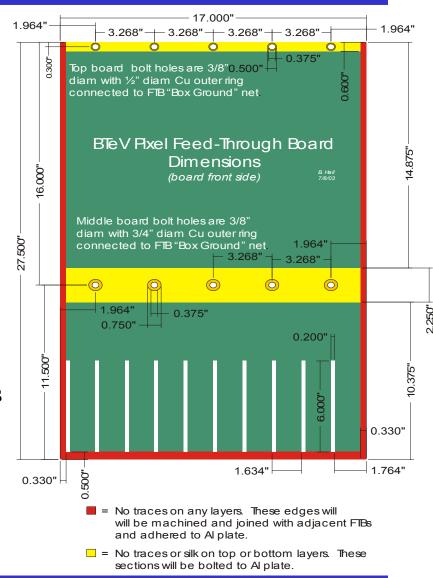


Feed-through Board (FTB)

WBS1.2

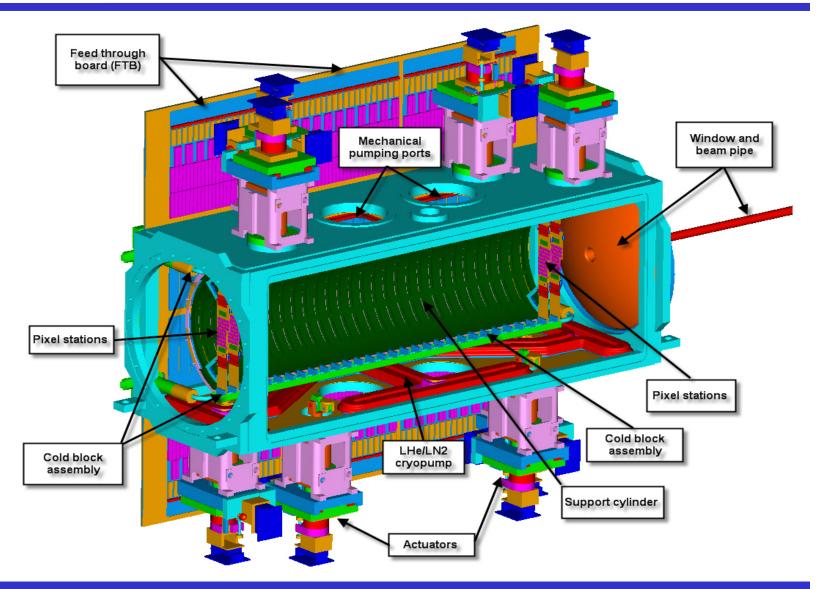


- Signal path: ROC- HDI- PIFC- FTB-PDCB-trigger/DAQ system
- Board size: 17"x27.5"; more than 16 layers
- Full size FTB prototype will be delivered next month
- Key for mechanical and electrical tests
- FTB layout is very dense and can benefit from any possible simplification





Pixel Detector Assembly





Fermilab: J. A. Appel, D. C. Christian, S. Cihangir, J. Fast, R. Kutschke, S. Kwan, M. Marinelli, L. Uplegger, J. Andresen, M. Bowden, G. Cardoso, H. Cease, C. Gingu, J. Hoff, A. Mekkaoui, M. Turqueti, R. Yarema, J. Howell, C. Kendziora, M. Kozlovsky, M. Larwill, C.M. Lei, A. Shenai, M.L. Wong, S. Austin, S.Jakubowski, R. Jones, G. Sellberg, M. Ruschman, J. Rausch, R. Sanders, E. Skup

Frascati: S. Bianco, F. Fabbri, M. Caponero, D. Colonna, A. Paolozzi

Iowa: C. Newsom, M. Divoky, J. Morgan

Milano: G. Alimonti, S. Magni, D. Menasce, L. Moroni, D. Pedrini, S.

Sala

Syracuse: M. Artuso, C. Boulahouache, J.C. Wang

Tennessee T. Handler, R. Mitchell, S. Berridge

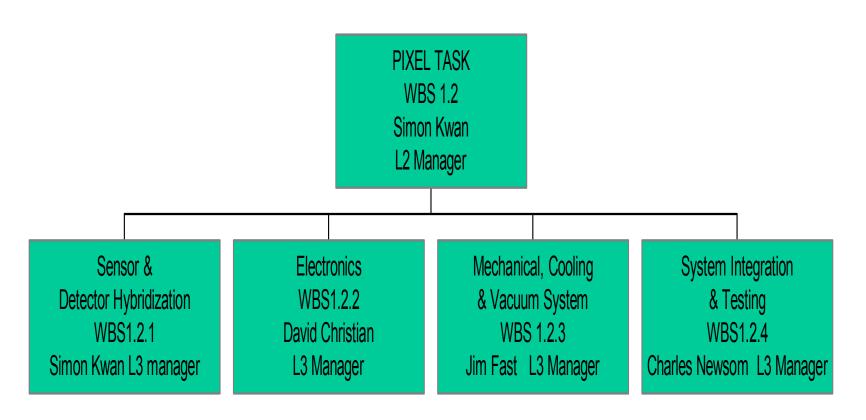
Wayne State: D. Cinabro, G. Bonvicini, A. Schreiner, A. Guiterrez, G.

Gallay, S. LaPointe

-Physicist

- Technical staff





Base cost: \$14.57M (Material: \$7.14M, Labor: \$7.43M)



Pixel Construction Cost

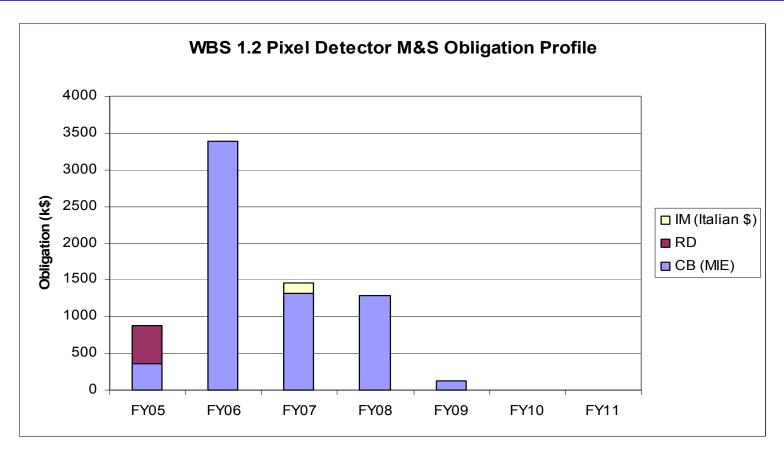
WBS 1.2

Activity ID	Activity Name	Base Cost (\$)		Labor Contingency (%)	Total FY05			Total FY08			Total FY05- 10
	Sensors and Pixel Detector Hybridization	2,277,593	47	32	463,135	1,689,904	1,149,138	0	0	0	3,302,177
	Pixel Detector Electronics	3,728,580	38	40	839,433	1,652,929	611,864	1,966,818	99,198	0	5,170,242
	Mechanical Cooling and Vacuum System	4,163,408	48	38	617,761	2,413,926	1,578,080	1,304,943	0	0	5,914,710
1.2.4	System Integration & Testing	3,538,862	54	52	405,261	1,146,831	2,371,276	1,118,661	335,725	0	5,377,754
	Pixel Detector Subproject Management	861,432	25	18	222,568	240,281	190,185	190,185	181,504	0	1,024,723
1.2	file_12_092004	14,569,875	44	41	2,548,158	7,143,872	5,900,544	4,580,606	616,427	0	20,789,607

- CD1 Review: Base \$15.5M Total \$21.65M (contingency ~ 40%)
- Move DCB to WBS1.9 + new quotes (e.g. readout chips, TPG) reduce base M&S by \$900K
- Increase labor and contingency (now 42.7%) following the CD1 reviewers' remark



M&S Obligation Profile by Fiscal Year WBS 1.2

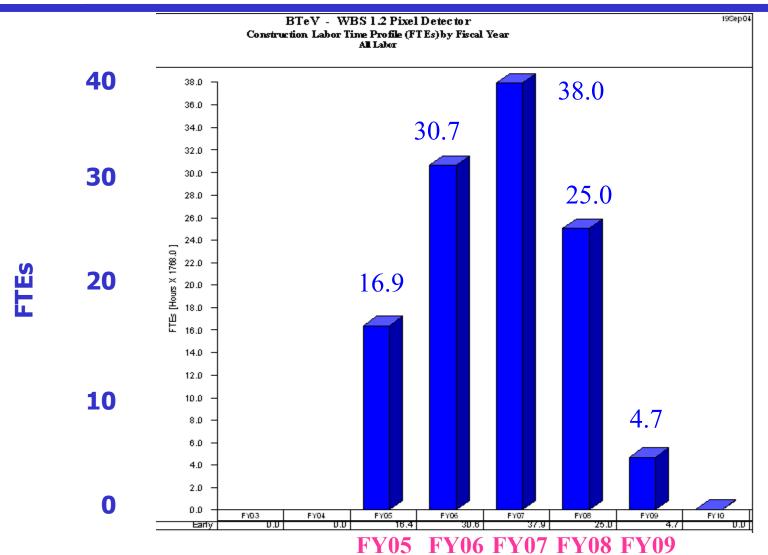


	FY05	FY06	FY07	FY08	FY09
CB (MIE)	355	3393	1322	1286	126
RD	517				
IM (Italian	\$)		143		



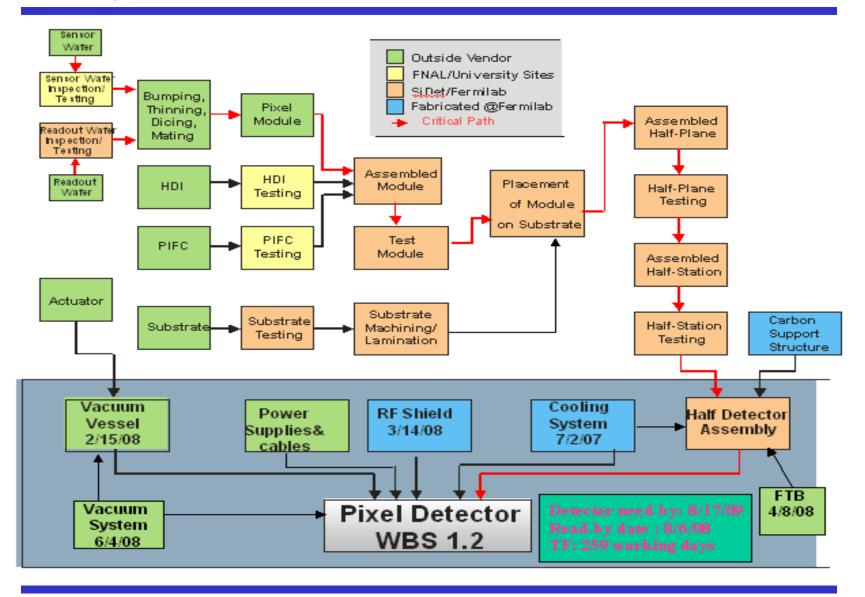
Labor Profile by Fiscal Year

WBS 1.2



Pixel Flow Diagram

WBS1.2



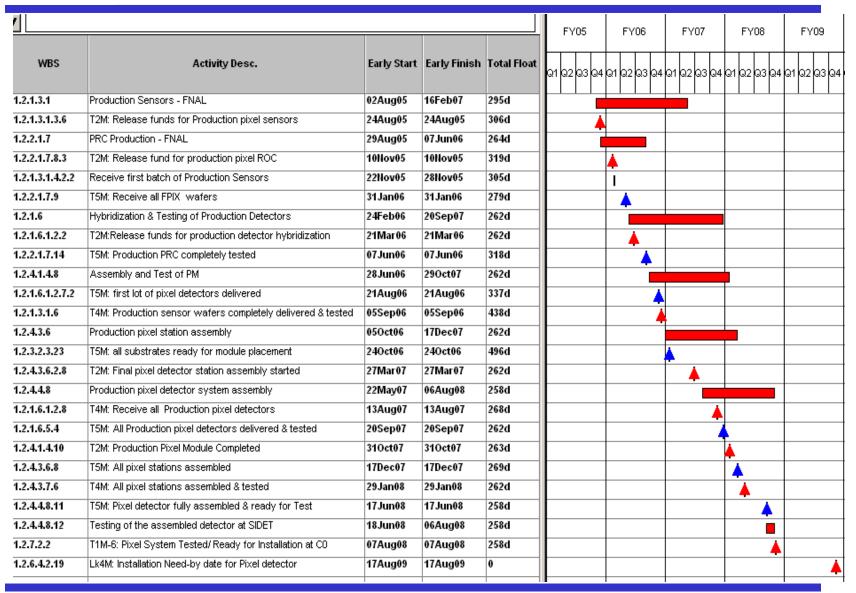


- Detector need-by date: August 17, 2009
- Scheduled completion date: August 6, 2008 giving a total float of 259 working days
- Pixel Detector will be installed as one piece (vessel with stations inside)
- Pixel Detector has many components but the critical path is the making the pixel modules, placing them on a substrate (half-plane and half-station), and assemble the half-stations into the two half-detectors. This is a sequence of production, assembly and testing steps. Because we have 1380 modules in total, the duration of the each sequence is long (10 months or more). To keep this tight schedule,
 - ➤ A lot of staggering in the activities
 - ➤ Place the orders early (sensor, ROC, hybridization)
 - DOE CD1 Report: advance the critical component procurement in 2005
 - ➤ Multiple paths/vendors
 - > Sustain the flow of parts and have more than one assembly/test line/shift
 - Engage qualified vendors early in QA and throughput discussion



Critical Path Gantt Chart

WBS1.2



Milestone	Date
T2M-3: Contract awarded for production pixel sensors	Nov 9, 2005
T2M-2: Contract awarded for production pixel readout chips	Jan 24, 2006
T1M-4: Contract awarded for production pixel detector hybridization	Jul 10, 2006
T3M-13: Vacuum System designed & approved for construction	Jul 24, 2007
T3M-14: Final pixel detector assembly started	Oct 12, 2007
T3M-15 Pixel modules completed (assembly & testing)	Apr 11, 2008
T1M-6: Pixel detector tested & ready to be shipped to C0	May 9, 2009

Need-by Date: August 17, 2009



Pixel Detector Risk Analysis

WBS1.2

Risks	Mitigation strategy
Bump bonding vendors not available or have unacceptable yield or throughput	Identify more vendors. Keep close contact with LHC experiments and have information about their schedule and vendors
Cannot achieve the vacuum required due to gas load much bigger than expected and we don't have enough space for larger pumps or cryopanels	Repeat outgassing test with a model which includes close to final components and full size FTB. Prototype the cryopumps
Pixel temperature control, cooling, and vacuum system do not work as designed.	We have put in our plan a system demonstrator program that will happen early in the construction phase to study this and various failure modes.



Responses to CD1 recommendations

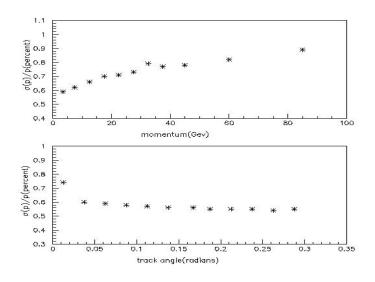
WBS1.2

- Develop more conservative schedule with significant more float (> 6 months)
 - > We have followed their recommendation. By moving a few procurements forward and move back the detector need-by date, we have achieved a float of about 1 year.
- Evaluating options for relaxing the funding profile constraints to achieve a more conservative approach
 - > DONE. We have increased the funding for FY05 to move up the production of sensors and speed up the module development.
- Evaluate schedule and performance impact of staging options
 - ➤ While we believe that the experiment will work with an efficiency of about 60% with say ½ of the pixel stations, to complete the installation of the other half of the pixel detector will lead to a long shutdown, estimated to be about 6 months or longer and with considerable risk to the forward tracking stations (which need to be removed first before the pixel vacuum vessel can be taken out). After careful consideration, we think that it's better to assign resources to guarantee the completion of the pixel detector on schedule and not pursue the staging option.



Technical Description of Straw Tracker WBS1.6

- Straws: chosen because of of small cell size (segmentation)
- Uses Atlas design as basis
- 0.8% Xo per station
- Tracking resolution: 150μm/view
- Momentum resolution better than 1% over full momentum and angle range



Straw size	4 mm, 8mm diameter
Central dead region	26 cm x 26 cm
Number of Stations	7
Z positions (cm)	96, 138, 196, 288, 332, 382, 725
Active Half size (cm)	27.2, 40.8, 61.2, 88.4, 102, 115.6, 197.2
Views per station	3
Layers per view	3
Total number of straws	26784
Total station thickness	0.8% X ₀
Total channels	53568
Readout	ASDQ + TDC(8 bits), sparsified

Momentum resolution



- 1.6.1 Straw Detectors (7 stations)
 - > the physical Detector.
- 1.6.2 Straw Electronics
 - includes front-end electronics, High and Low Voltage power supplies and cables.
- 1.6.3 "Other" Mechanical Subsystems
 - ➤ Gas system, temperature control...
- 1.6.4 Hardware and Software specific to Straw Detector
 - > Test Stations with database connections
 - Fast Interlocks and Slow Controls
- 1.6.5 Management

Base cost: \$10.0M (Material: \$5.0M, Labor: \$5.0M)

Assembled in

- Modules

groups of 48 straws

(More or less to scale) Station # 6 HalfView 231.2 cm Class Reads Dead Region Gas Manifold Hole size=6.8mm inner diameter Mod type 1 (96 4mm diameter Straws, gas Manifold and 27 cm dead region) Mod type 1=96 straws (short straw) Mod type 2 (48 4mm diameter Straws, 27 cm dead region) Mod type 3 (48 4mm diameter Straws)

total=864 straws

17 modules/HalfView

Mod type 2 = 48 straws

Mod type 3 = 720 straws

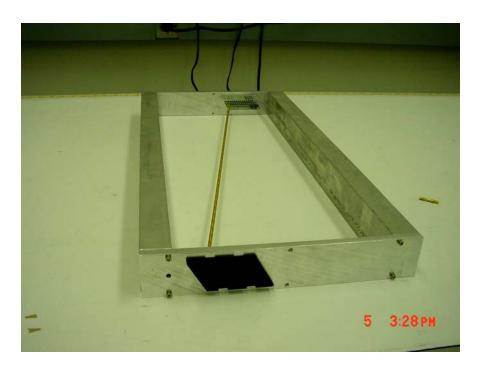
4mm modules have 3 planes of 16 straws

module is 6.8cm high (6.4 mm straws+2mm gap each side)

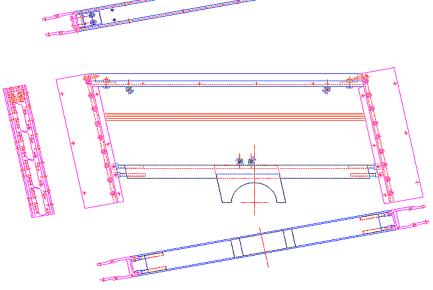


Straw Detector Stations 1 & 2 WBS1.6

Straw Length = 54 cm 384 Straws/View 1152 Straws/station



Station 1 "Prototype" Frame

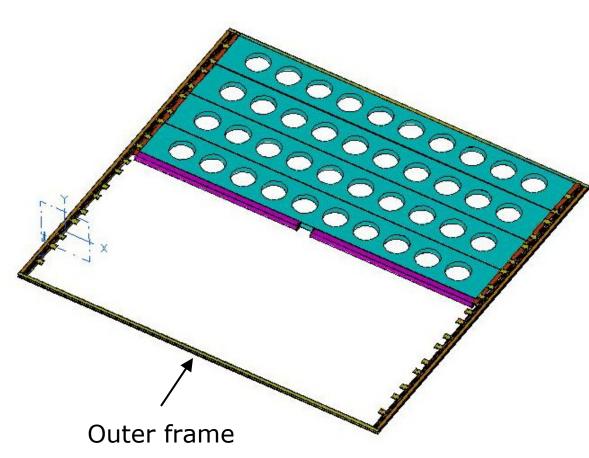


Station #1 U,V HalfView Frame.

X View is simple rectangular shape



Station 7 – View Outer Frame (One VIEW) WBS1.6



- Station 7 constructed of super-modules
- Super-module attached at ends to Outer Frame
- Outer Frame supports and aligns super-modules
- Each Outer frame supported individually from above by connecting rods

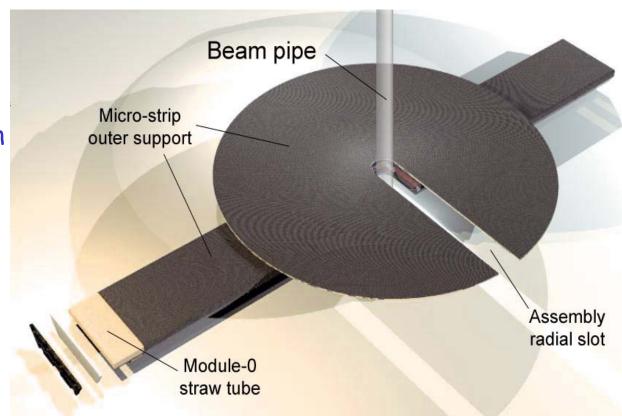


Straw MOX module – Silicon Support WBS1.6

New Straw module designed at Frascati to support the forward Silicon stations. Replaces the 2 modules in X-view that surround the beam-pipe. Supported independently of Straw station

Straws are embedded in rohacell so no tension needed to keep them straight. Module has carbon fiber shell.

Carbon fiber disk is attached for Silicon support





Straw Detector Participants

WBS 1.6

- Fermilab: A.A. Hahn, P. Kasper, H. Cease, J. Howell, J. Krider, A. Lee, D. Olis, T. Tope, W. Stuermer, C. Serritella, Z.Shi, D. Butler, B. Pritchard, Y. Orlov
- Frascati: F. Bellucci, M. Bertani, L. Benussi, S. Bianco, M. A. Caponero, F. Fabbri, F. Felli, M. Giardoni, G. Mensitieri, A. La Monaca, E. Pace, M. Pallotta, A. Paolozzi, B. Ortenzi
- Southern Methodist University: T. Coan, M. Hosack
- University of Houston: K. Lau, B. Mayes, G. Xu, S.Subramania, A. Daniel, M.Ispiryan
- University of Virginia: M. Arenton, S. Conetti, B. Cox, A. Ledovskoy, M.Ronquest, D. Smith, D. Phillips, H. Powell, W. Stephens
 -Physicist
 - -Grad Students
 - Technical staff

WBS 1.6 A. Hahn 1.6.5 1.6.1 1.6.2 1.6.3 1.6.4 Management Other Mech. Straw Straw Integration & D.Olis ME Electronics Subsytems **Testing** Detectors W.Stuermer EE J. Krider W. Stuermer D. Olis P.Kasper J. Krider PE \$6.0M \$733k \$204k \$2.2M \$923k **FNAL Site** Frascati Site **U** Houston Site **SMU Site UVa Site** A. Hahn F. Fabbri K.Lau T. Coan B. Cox

Base cost: \$10.0M (Material:\$5.0M, Labor:\$5.0M)



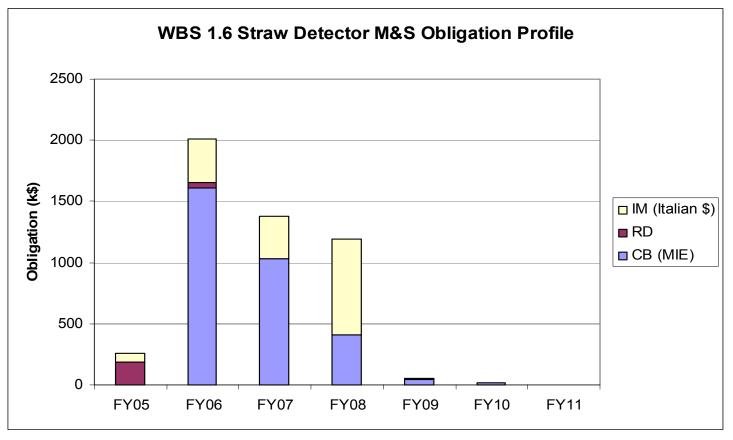
Straw Tracker Construction Cost

WBS 1.6

Activity ID	Activity Name	Base Cost (\$)	Material Contingency (%)		Total FY05		Total FY07				Total FY05-10
<u>1.6.1</u>	Straw Chambers	6,010,806	23	28	381,426	2,942,786	2,180,499	1,946,006	92,419	0	7,543,136
1.6.2	Straw Detector Electronics	2,168,546	27	36	456,470	894,403	985,464	486,232	8,652	0	2,831,221
1.6.3	Mechanical Gas Calibration & Other Support Systems (FNAL SMU)	733,011	30	37	40,769	199,303	170,646	553,044	18,213	0	981,975
<u>1.6.4</u>	Integration & Testing (all)	204,034	31	87	59,302	95,979	69,900	41,058	19,039	0	285,277
II I	Forward Tracker Straw Detector Subproject Management	923,474	22	10	110,421	265,672	272,819	265,672	71,115	44,500	1,030,201
1.6	file_16S_13Sep04	10,039,870	25	28	1,048,389	4,398,143	3,679,327	3,292,013	209,438	44,500	12,671,810

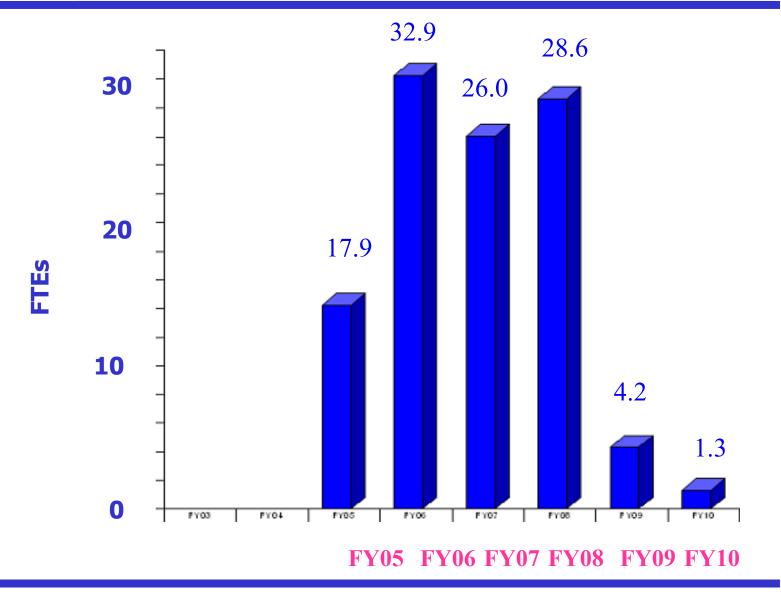


M&S Obligation Profile by Fiscal Year WBS 1.6



	FY05	FY06	FY07	FY08	FY09	FY10
CB (MIE)		1613	1033	406	41	15
RD	184	42				
IM (Italian	77	356	349	783	8	0



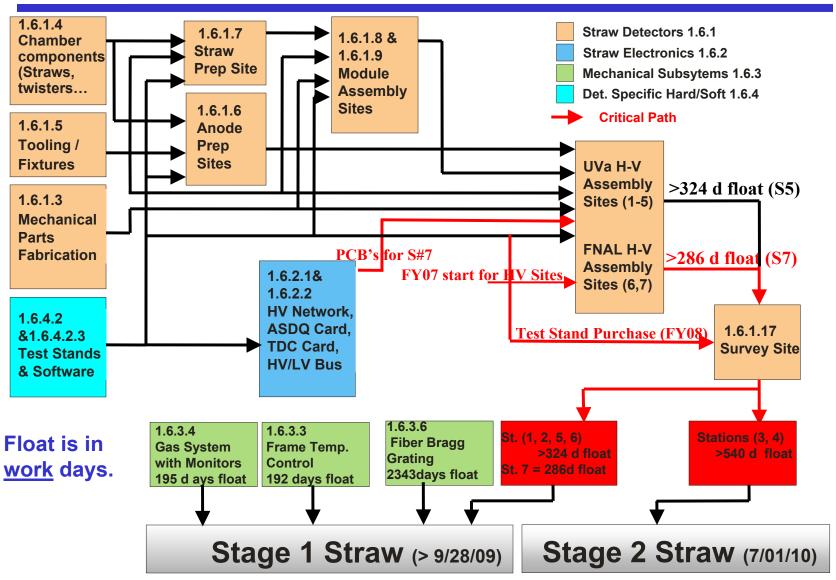


Director's CD-2/3a Review of the BTeV Project – September 28-30, 2004 BTeV Tracking System - Simon Kwan



Description of Straw Project Flow

WBS 1.6





WBS 1.6 Staged Gantt Chart

4			FY0	4		FY05		F,	Y06		FY07		FY08	FY09
WBS	Activity Desc.	Total Float	Q1 Q2 G	Ω3 Q4	Q1 G	Q2 Q3	Q4	Q1 Q2	2 Q3 Q	1 Q1	Q2 Q3	Q4	Q1 Q2 Q3 Q	4 Q1 Q2 Q3
1.6.1.3.3.3.2.16	T5M: S#7 Supermodules Shells Ready, H-V1,2,3	358d	-				'							
1.6.1.3.3.3.2.17	T5M:S#7 Supermodules Shells Ready, H-V 4	334d											4 77	
1.6.1.3.3.3.2.18	T5M: S#7Supermodules Shells Ready,H-V 5	310d												
1.6.1.3.3.3.2.19	T5M:S#7 Supermodules Shells Ready,H-V 6	286d											A	
1.6.1.4.1.2	Straw Production Ordering -HOUSTON	390.07d]					
1.6.1.4.3.2	Wire Centering Device Production Ordering - HOUSTON	324.01d												
1.6.1.6	Anode Wire Sites (UVa, SMU)	239.80d												
1.6.1.7	Straw Preparation Site (UH)	324.01d												
1.6.1.10.1	Straw Station #1 Half-View Assembly Site (UVa)	353.62d									√	1 ,		
1.6.1.10.2	Straw Station #2 Half-View Assembly Site (UVa)	353.62d	Ha	14	7	7:0		-				Y		
1.6.1.10.3	Straw Station #3 Half-View Assembly Site (UVa)	353.62d	112		† ▼	10	W	/						
1.6.1.10.4	Straw Station #4 Half-View Assembly Site(UVa)	353.62d							<			¥.	٦,,	
1.6.1.10.5	Straw Station #5 Half-View Assembly Site(UVa)	324.01d	Sit	es										
1.6.1.10.6	Straw Station #6 Half-View Assembly Site (FNAL)	378.17d												
1.6.1.10.7.2	Straw Station #7 Production - FNAL	286d												
1.6.1.11	Survey and Test Station Site (FNAL)	286d		Fe	d by	all	ΗV	site	S					
1.6.2.2.1.3.18	T5M: HV Network Card for S#3	369.84d									_			
1.6.2.2.1.3.21	T5M: HV Network Card for S#6	378.17d									<u> </u>			
1.6.2.2.1.3.22	T5M: HV Network Card for S#7	314.80d											<u> </u>	+
1.6.2.2.2.4.18	T5M: Preamp Board for S#3	376.84d									_			11
1.6.2.2.2.4.21	T5M: Preamp Boardfor S#6	385.17d									À		ıns	tallation
1.6.2.2.4.22	T5M: PDB for S#7	309.80d									-			

Critical Path Analysis

WBS 1.6

- Straw Stations ready for Installation
 - Critical path is primarily set by funding profile
 - FY05
 - Continue Design Work
 - » Frames, Front End Electronics, TDC ASIC....
 - FY06
 - Start major procurements
 Straws, Twisters, ASDQ's,...
 - Start Anode, Straw, and Module Production Sites.
 - FY07
 - Start Half View Assembly Sites
 - Production of Front End Electronics
 - ➤ The current production scheme builds (S3,S4,S1,S2,S5) and (S6, S7) at two parallel Half View production sites.
 - The production time scales are set by various assumptions on assembly lines (2/site) and a single shift. These assumptions (# sites, # assembly lines, # shifts, and order of station production) could be changed.



Straw Level 3 Milestones + WBS1.6

WBS1.6	Forward Straw Tracker	Date
1.6.7.4.1	T3M-38:PO Awarded: Production ASDQ Chips *	October 10, 2005
1.6.7.4.2	T3M-39:ASDQ Procurement completed	August 3, 2006
1.6.7.4.3	T3M-40:Straw Preparation Site Functional	March 7, 2006
1.6.7.4.4	T3M-41: Half-View Production/ Assembly Sites Functional	February 7, 2007
1.6.7.4.5	T3M-42: Station 1 ready for Installation *	April 3, 2008
1.6.7.4.6	T3M-43: Station 7 ready for Installation	August 26, 2008

* Also a Level 2 Milestone

+ With distributed Float



Responses to CD1 recommendations

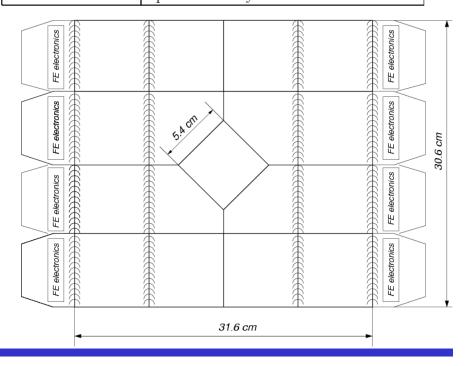
- **WBS1.6**
- Select the straw material, straw diameter, and wire diameter within this year. Clear work plan should be provided.
 - We will acquire new Copperized Kapton Straws and subject them to radiation tests. We will also test 30 μm Anode wire (currently use 25 μm wire). We will set up a work plan.
- Put Additional Effort into aging test
 - > UH and UVa will test new straw materials (and anodes) and UH, UVa, and SMU have proposal to undertake Rad Damage test at IUCF.
- Produce more prototypes (preferentially in all production sites) and test.
 They should be built with production components and tooling as much as possible
 - > This is consistent with our Station 3 prototype effort
- Move up production schedule by ~6 months
 - > DONE
- Strengthen management with a project engineer
 - > Production engineer and site managers now added to the org. chart.



Technical Description of Silicon Tracker WBS1.7

- Silicon Strips: simple single sided p+/n design (CMS design)
- 7 stations
 - > 3 in dipole fringe field
 - > 3 before RICH
 - ➤ 1 after RICH
- Coverage from beam pipe to ±15.5cm from the beam
- Each station has 3 planes of 320
 μm thick SMD with 100 μm pitch
- Each detector is 7.9 cm x 7.9 cm
- Four detectors form one ladder with readout at both ends
- New readout chip (FSSR) using 0.25μm CMOS; 1st prototype tested
- 2nd prototype submission planned for early next year

Property	Value
Silicon Sensors	$\sim 7.9 \times 7.9 \ cm^2$, p-on-n type
Pitch	$100~\mu m$
Thickness	$320 \ \mu m$
Sensor configuration	4 ladders with 4 sensors each
Coverage	$30.6 \times 31.6 \ cm^2$
Central Hole	$5.4 \times 5.4 \ cm^2 \ (7 \times 7 \ cm^2 \ for \ last \ station)$
Total Stations	7
Z Positions	85.5, 127.5, 185.5, 277.5, 321.5, 371.5, 714.5
Views per Station	3 (X,U,V)
Channels per view	6,144
Total Channels	129,024
Readout	Sparsified Binary

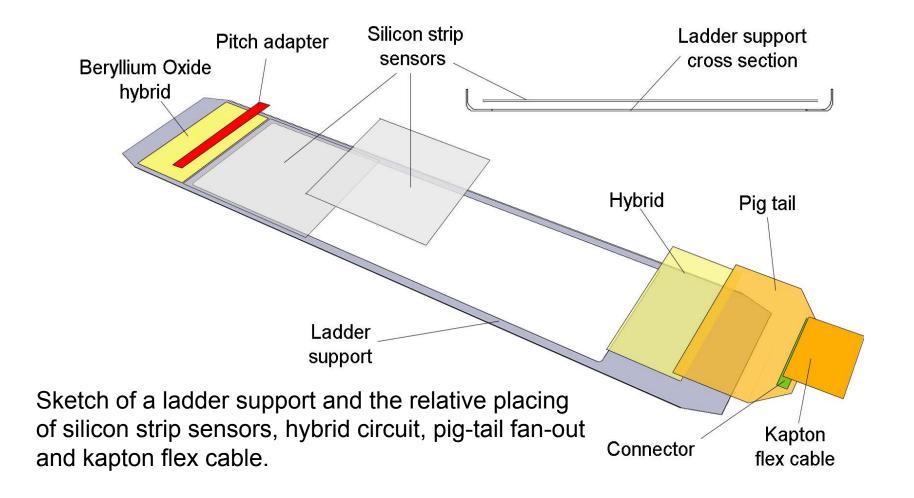




Base cost: \$7.5M (Material: \$3.7M, Labor: \$3.8M)

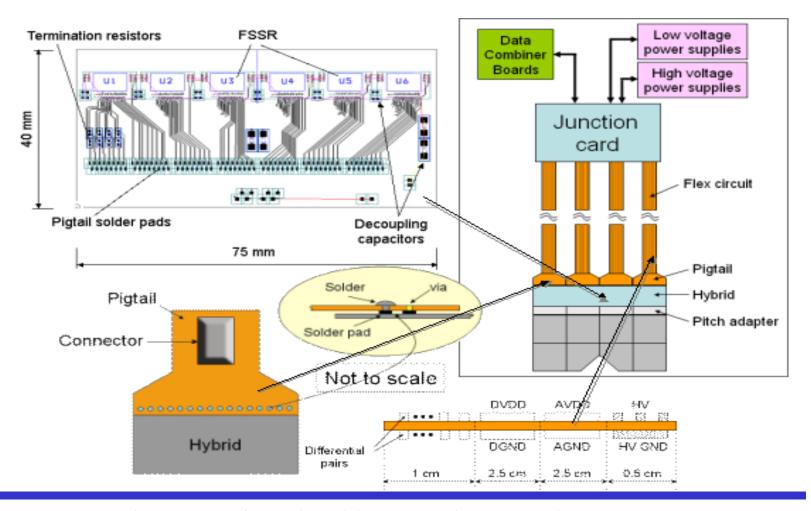
- Sensors
- Readout Chips
- Electronics Packaging & DA
 - ➤ Hybrids, Flex's, Junction Cards, Power Supplies, Cabling and DCB's
- Mechanics
 - ➤ Inner & Outer Supports
- Cooling
- Ladder Assembly
- System Integration & Testing
 - ➤ Detector Prototypes & Tests, Control & Monitor, Detector Specific Software





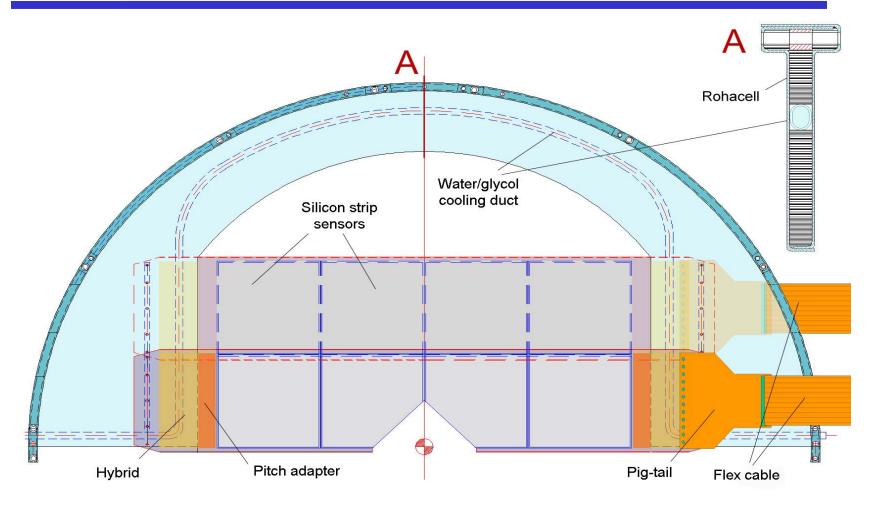


Benefit from CDF RUN IIB experience



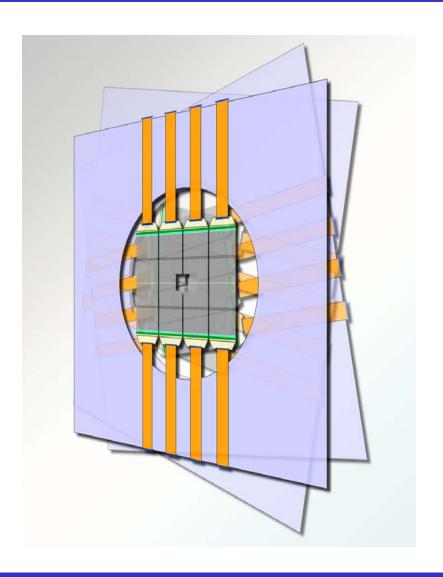


Silicon Strip Detector Half Plane Support WBS1.7









3 views:

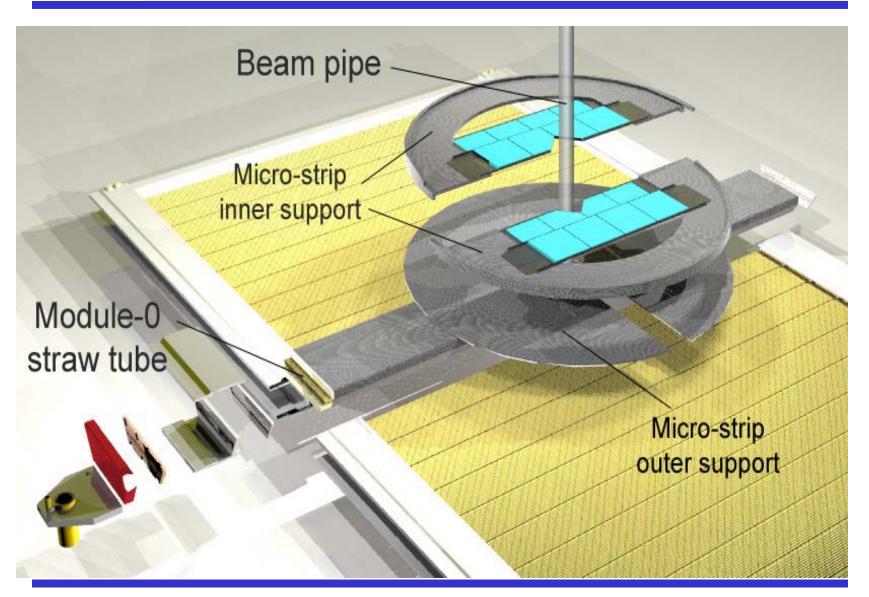
X: 0° (horizontal)

U: 90° + 11.3°

V: 90° - 11.3°



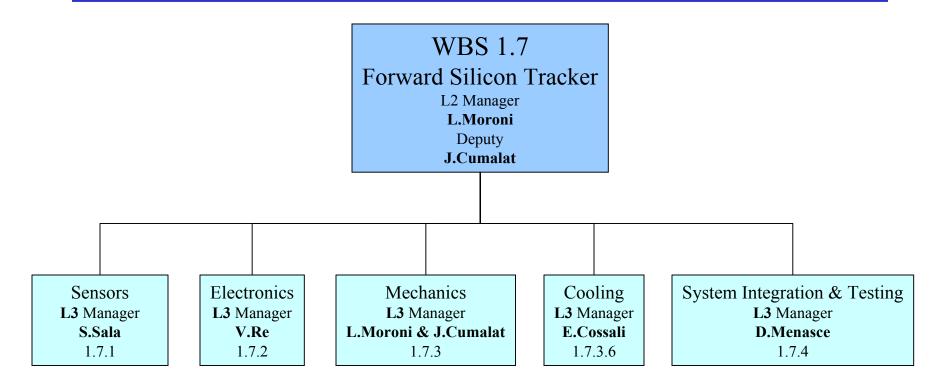
Forward Tracker Station Assembly





Silicon Tracker Participants

- **WBS 1.7**
- Colorado University: J.Cumalat, P.Rankin, Eric Erdos
- Fermilab: J. Andresen, G. Cardoso, C. Gingu, J. Hoff, M. Hrycyk, A. Mekkaoui, R. Yarema, J. Andresen, K. Knickerbocker, A. Dyer
- Frascati: M. Caponero, D. Colonna, A. Paolozzi, F. Fabbri, S. Bianco
- Insubria University: P. Ratcliffe, M. Rovere
- INFN Milano: G. Alimonti, M. Citterio, S. Magni, D. Menasce, L. Moroni, D. Pedrini, S. Sala, S. Erba, P. D'Angelo, S. Latorre, M.Malatesta
- INFN Pavia: G.E. Cossali, P.F. Manfredi, M. Manghisoni, M. Marengo, L. Ratti, V. Re, M. Santini, V. Speziali, D. Di Pietro, G. Traversi, K. Fisher, L. D'Angelo
 - Technical staff



Base cost: \$7.5M (Material: \$3.7M, Labor: \$3.8M)



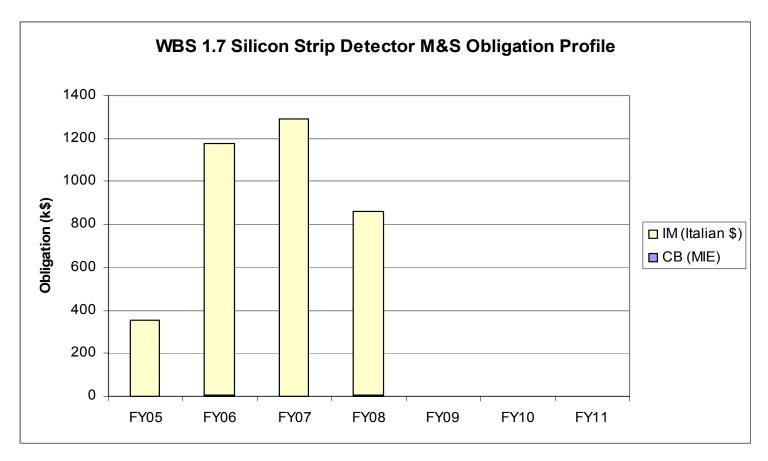
Silicon Tracker Construction Cost

WBS1.7

Activity ID		Base Cost (\$)	Contingency		Total FY05		Total FY07	Total FY08	Total FY09	Total FY10	Total FY05-10
<u>1.7.1</u>	Sensors (SM)	1,209,665	25	29	0	357,979	1,146,983	7,129	0	0	1,512,091
<u>1.7.2</u>	Electronics	2,561,906	31	28	651,532	1,014,537	953,955	625,718	61,906	0	3,307,648
<u>1.7.3</u>	Mechanics & Cooling	1,158,348	53	39	165,325	402,081	443,834	630,359	47,843	0	1,689,442
<u>1.7.4</u>	Integration	2,062,839	46	37	574,803	565,529	630,708	1,114,065	0	0	2,885,104
	Detector Subproj Mgmt	462,468	30	27	59,044	165,454	163,507	156,598	45,509	0	590,113
1.7	file_17 S _092204	7,455,226	35	33	1,450,704	2,505,579	3,338,988	2,533,869	155,258	0	9,984,398

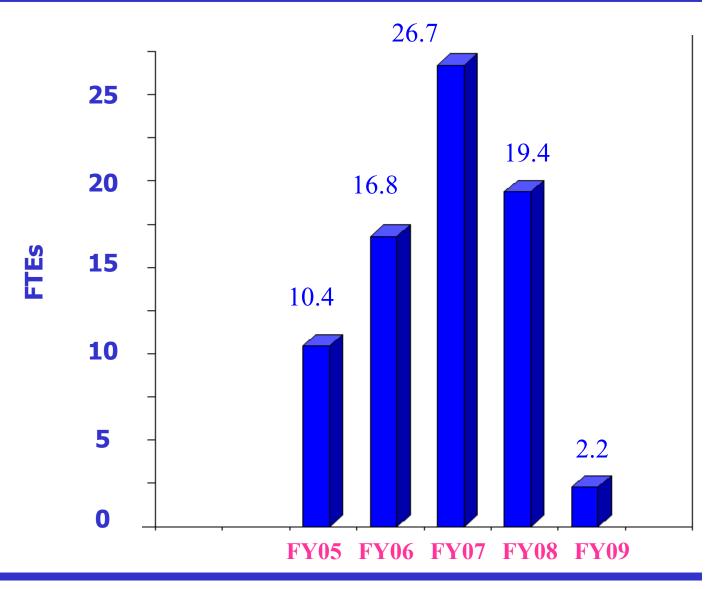


M&S Obligation Profile by Fiscal Year WBS1.7



	FY05	FY06	FY07	FY08	FY09
CB (MIE)		4		4	
RD					
IM (Italian	354	1171	1290	855	

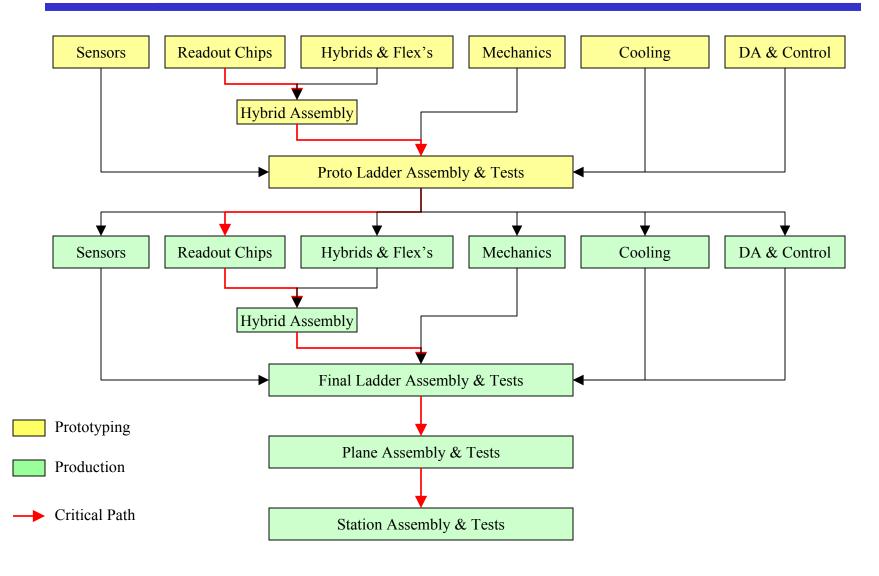






Description of Project Flow

WBS 1.7





Gantt Chart for Strip Detector WBS1.7

BTeV - WBS 1.7 Forward Tracker Strip Detector Barchart for Critical Path Analysis Sorted by Float

Planned	777777777777777777777777777777777777777
Critical	***************************************
Late Dates	-
Milestone	U
Progress	
Summary	
Float	

										Fluat				
Activity ID	Activity Description	Activity Type	Duration	Hoat	Early Start	Early Finish	Late Start	FY04	FY05	FY06	FY07	FY08	FY09	FY10
2.1.5.1.1.4	La yout Pass Two IC Des	ASAP	40d	247d	05 No v04	07Jan05	01 No v05	5.1.1.4	7					
2.1.3.1.1.4	Sim Layout, Incorporate Des Changes & Revise Doc, as necessa	ASAP	30d	247d	19 No v04	07Jan05	15 No v05	B.1.1ŗ ≠						
2.1.5.1.1.5	Sim Layout, Incorporate Des Changes & Revise Doc, as necessa	ASAP	30d	247d	19Nov04	07Jan05	15 No v05	5.1.1.5	_					
2.1.1.1.3	Vend Man fucture & Del Pass T wo Protos	ASAP	60d	247d	21 Fe b 05	13May05	005 100	2.1.1.1.						
2.1.1.1.4	Test Pass Two IC Protos	ASAP	40d	247d	16 May 05	12Jul05	03 May06		1 - 2					
2.1.3.1.3	Test Pass Two IC Protos	ASAP	40d	247d	16 May 05	12Jul05	03 May 06		1 - 2					
2.1.5.1.4	Test Pass Two IC Protos	ASAP	40d	247d	16 May 05	12Jul05	03 May 06	_	1.	_				
2.1.6.1.4	Layout Final IC Design	ASAP	50d	247d	13 Oct 05	23De c05	02 Oc t06		.6.1.4					
2.1.2.2.3.1	Vend Man fucture & Del Pre-Prod Run of Final ICs	ASAP	60d	247d	09Feb06	03May06	01 Fe b 07		1.2.2.3	₣—	Y			
2.1.2.2.4	Test Pre-Prod Run of Final ICs	ASAP	40d	247d	04May06	29Jun06	26 Apr 07			2 + 0	-			
2.1.4.1.10	Test Pre-Prod Run of Final ICs	ASAP	40d	247d	04May06	29Jun06	26 Apr 07	 	2.1.4.1	-	Ox.			
2.1.6.1.11	Test Pre-Prod Run of Final ICs	ASAP	40d	247d	04May06	29Jun06	26 Apr 07	-	2.1.6.1	1=0				
2.2.3.13	Test Assembled Preproduction Hybrids for Station Tests	ASAP	40d	247d	12 Se p06	06No v06	04Se p07		2.1.0.1	2.3.13	 			
2.2.8.4	Test Assembled Preproduction Hybrids for Station Tests	ASAP	40d	247d	12 Se p06	06No v06	04Se p07	i –	2	2.8.	4	io iii		
2.2.4.8.1	Manufacture 1st Shipment of Hybrid	ASAP	90d	247d	08 Fe b 07	14Jun07	04Feb08	i						
2.2.9.1	Manufacture 1st Shipment of Hybrid	ASAP	90d	247d	08 Fe b 07	14Jun07	04Fe b08	i —		_		0 0		
2.2.4.9.1	Manufacture Final Shipment of Hybrid	ASAP	30d	247d	03 Jul07	14Aug07	26 Jun08	; —		-	4.9.1 []			
2.2.9.3	Manufacture Final Shipment of Hybrid	ASAP	30d	247d	03 Jul07	14Aug07	26 Jun08	 			9.			
2.2.4.9.5	Vend Assembles & Tests Hybrids for Ladder Production	ASAP	40d	247d	13 Se p07	07No v07	08 Se p08	<u> </u>			4.9.5			
2.2.9.4	Vend Assembles & Tests Hybrids for Ladder Production	ASAP	40d	247d	13 Se p07	07No v07	08 Se p08				2.94	4		
2.2.4.9.6	Test Assembled Production Hybrids for Ladder Production	ASAP	60d		27 Se p07	21De c07	22 Se p08	!		-	-	" 		
2.2.9.5	Test Assembled Production Hybrids for Ladder Production	ASAP	60d		27 Se p07	21De c07	22 Se p08	<u> </u>		2.4	4.9. ₽	-		
2.2.4.9.8	Prod Hybrids ready for Ladder Assembly	ASAP	30d		08 No v07	21De c07	03 No v08	-		<u> </u>	1	Γ—		
4.2.2.5.3	Test Ladder Prod at SiDet	ASAP	138d		17 De c07	03Jul08	10 De c08	-		_	2.4.9.8	-	×	
4.2.3.1	Assemble & Test Ladders at SiDet	ASAP	138d		17 De c07	03Jul08	10 De c08	-		-4	2.2.5	-	e c	<u> </u>
7.2.0.1	Manufacture of Strategies at Strategies	TOWN F	1300	2410	11.00.00	0330100	100000	<u>i </u>			4. 2. 3. 1		6 6	<u> </u>

- Staged Installation
 - > Stage 1: Stations 1, 2, 6, and 5 in FY09 shutdown
 - > Stage 2: Rest of the stations in FY10 shutdown
- The shortest Total Float in the Forward Silicon Strip project is 247 days (for FY09 shutdown)
 - ➤ i.e. any delay up to 12 months can be absorbed by our schedule without impacting the deadline for installation.
 - > Stations that will be installed in FY10 will have a minimum float of 449 days.



Response to CD-1 Review Recommendations WBS1.7

- From CD-1 Report:
 - The silicon strip tracking detector was **found to be in good shape** at the CD-1 review. The positive news about **INFN funding** makes the schedule for the silicon strip tracker **even more robust.**
- ➤ Indeed all the funding constraints were removed from the schedule and the float went from 112 days up to 247 days.
 - About 1 year delay can be safely absorbed!



Summary for WBS 1.2, WBS 1.6, and WBS 1.7

More information on the Pixel (WBS 1.2), Straw (WBS 1.6) and Silicon Strip Tracker (WBS 1.7) is available in the breakout sessions.

WBS 1.2

- Overview D. Christian
- Sensor & hybridization S. Kwan
- Electronics G. Cardoso
- Substrate & half-plane assembly CM Lei
- Vacuum system H. Cease
- Pixel Detector assembly J. Fast
- Test beam C. Newsom
- Cost and Schedule S. Kwan

WBS 1.7

- Overview L. Moroni
- Readout chip V. Re
- Readout electronics G. Cardoso
- FBG sensors for BTeV Tracking Detectors S. Bianco
- Cost and Schedule L. Moroni

WBS 1.6

- Activities at University of Houston (K.Lau)
- Module 0X (S. Bianco)
- Activities at SMU (T.Coan)
- Activities at UVa (B.Cox)
- Latest results from Straw Test Beam Run (A.Ledovskoy)
- Acoustic Method for Wire Tension Measurement (M. Hosack)
- BTeV Straw Design and Prototyping Efforts (A.Hahn)
- Straw Chamber Assembly (Y. Orlov)
- BTeV Straw Detector Simulations (P.Kasper)
- Straw Response to Lehman CD1 (A.Hahn)

BTeV Co

Conclusion

- The BTeV tracking system has three elements: Pixel vertex detector, forward silicon tracker, and forward straw detector
- For all three detectors:
 - ➤ Baseline technical designs exist
 - Organization structure established
 - ➤ Detailed WBS leading to a base cost estimate and resource-loaded schedule for the construction of the baseline detector
 - > We are ready to move on to the next phase of the project



Backup Slides



Pixel Glossary of Terms WBS1.2

- HDI High Density Interconnect
- PIFC Pixel Interconnect Flex Cable
- FTB Feed-through Board
- TPG Thermal Pyrolytic Graphite
- PGS Pyrolytic Graphite Sheet
- LN2 Liquid Nitrogen
- LHe Liquid Helium



Straw Glossary of Terms

- **WBS 1.6**
- Module : basic construction unit consisting of 48 straws
- Half-Views: Each Straw Station is made of 3 views (X, U, V). Each View is divided into two "Half-Views", in order to install detector around an existing beam pipe. Each Half-View is an independent working detector.
- ASDQ chip Amplfier, Shaper, Discriminator and Charge chip; designed by the Upenn group and used in CDF COT
- MOX Module O (closest to the beam pipe) X view



Silicon Strip Glossary of Terms

WBS 1.7

- FSSR: Fermilab Silicon Strip Readout Chip
- DCB: Data Combiner Board (note: Pixel and silicon strip will use the same type of DCB)
- DA: Data Acquisition
- FBG: Fiber Bragg Grating

Milestone	Date
T2M-3: Contract awarded for production pixel sensors	Aug 24, 2005
T2M-2: Contract awarded for production pixel readout chips	Nov 10, 2005
T1M-4: Contract awarded for production pixel detector hybridization	Mar 21, 2006
T3M-13: Vacuum System designed & approved for construction	May 14, 2007
T3M-14: Final pixel detector assembly started	Mar 27, 2007
T3M-15 Pixel modules completed (assembly & testing)	Nov 1, 2007
T1M-6: Pixel detector tested & ready to be shipped to C0	Aug 6, 2008

Need-by Date: August 17, 2009

Total Float: 259 days

Schedule Contingtency

WBS1.2

Schedule contingency

- ➤ Placed before key milestones or activities on critical or near critical path
- ➤ Nominally zero duration
- ➤ Distribute float throughout the duration of the project
- > Typically increase duration of activity by 20 to 30%.

11Aug05						FY05	FY06	FY07	FY08	FYOS
WBS	Activity Desc.	Early Start	Early Finish	Sch. Cont.	Total Float	\vdash		Q1 Q2 Q3 Q4		
.2.1.3.1.3.1	SC: Production sensor order schedule contingency task	11Aug05	11Aug05	30d	295d					' ' '
.2.1.3.1.3.6	T2M: Release funds for Production pixel sensors	24Aug05	24Aug05		306d	4				
.2.3.2.2.7.3	SC: Substrate design schedule contingency	06Sep05	06Sep05	50d	291d					
.2.2.1.7.8.1	SC: Production PRC schedule contingency	04Nov05	04Nov05	30d	264d					
.2.2.1.7.8.3	T2M: Release fund for production pixel ROC	10Nov05	10Nov05		319d		<u> </u>			
.2.1.3.1.4.2.7	SC: Production sensor delivery schedule contingency task	10Jan06	10Jan06	30d	334d					
.2.1.3.1.5.2.7	SC: Production sensor delivery schedule contingency task	11Jan06	11Jan06	30d	438d		i i			
.2.2.1.7.9	T5M: Receive all FPIX_wafers	31Jan06	31Jan06		279d		<u> </u>			
.2.1.5.2.1.1	SC: Pre-Production pixel detectors test schedule contingency	17Feb06	17Feb06	20d	182d		 T			
.2.1.6.1.1.1.6	SC: Production detector hybridization procurement contingency task	21Mar06	21Mar06	20d	262d		<u> </u>			
.2.1.6.1.2.2	T2M:Release funds for production detector hybridization	21Mar06	21Mar06		262d		<u> </u>			
.2.4.1.4.7.4	SC: Production pixel module assembly/test schedule contingency	03Aug06	03Aug06	30d	363d		- -			
.2.3.6.3.10.3	SC: Cooling system design schedule contingency	04Aug06	04Aug06	50d	369d		i			
1.2.1.3.1.5.3.7	SC: Production sensor schedule contingency	05Sep06	05Sep06	30d	438d					
.2.1.3.1.6	T4M: Production sensor wafers completely delivered & tested	05Sep06	05Sep06		438d			1		
.2.4.3.6.2.7	SC: Pixel station assembly schedule contingency	27Mar07	27Mar07	30d	262d					
.2.4.3.6.2.8	T2M: Final pixel detector station assembly started	27Mar 07	27Mar07		262d			<u> </u>		
.2.4.4.8.2.4	SC: Pixel half-detector assembly/test schedule contingency	03Jul07	03Jul07	20d	268d					
.2.1.6.1.2.7.5.4	SC: Production detector hybridization delivery schedule contingency	16Jul07	16Jul07	60d	289d					
.2.1.6.1.2.8	T4M: Receive all Production pixel detectors	13Aug07	13Aug07		268d			_		
.2.1.6.5.3	SC: Production pixel detector testing schedule contingency task	20Sep07	20Sep07	20d	262d					
.2.4.1.4.10	T2M: Production Pixel Module Completed	310ct07	310ct07		263d				<u> </u>	
.2.4.3.7.5	SC: Pixel station test schedule contingency	29Jan08	29Jan08	15d	262d				<u> </u>	
.2.4.3.7.6	T4M: All pixel stations assembled & tested	29Jan08	29Jan08		262d				À	
.2.7.2.2	T1M-6: Pixel System Tested/ Ready for Installation at C0	07Aug08	07Aug08		258d					
.2.6.4.2.19	Lk4M: Installation Need-by date for Pixel detector	17Aug09	17Aua09		0					



Critical Activities Gantt Chart With Distributed Float

WBS1.2

250ct05						FY05	FY06	FY07	FY08	FY09
WBS	Activity Desc.	Early Start	Early Finish	Sch. Cont.	Total Float	H			Q1 Q2 Q3 Q4	
1.2.1.3.1.3.1	SC: Production sensor order schedule contingency task	14Sep05	250ct05	30d	118d					
1.2.3.2.2.7.3	SC: Substrate design schedule contingency	01Nov05	11Jan06	50d	166d					
1.2.1.3.1.3.6	T2M: Release funds for Production pixel sensors	08Nov05	08Nov05		122d					
1.2.2.1.7.8.1	SC: Production PRC schedule contingency	06Dec05	16Jan06	30d	82d					
1.2.2.1.7.8.3	T2M: Release fund for production pixel ROC	23Jan06	23Jan06		137d		A			
1.2.1.3.1.4.2.7	SC: Production sensor delivery schedule contingency task	24Mar06	04May06	30d	138d					
1.2.1.3.1.5.2.7	SC: Production sensor delivery schedule contingency task	27Mar06	05May06	30d	212d					
1.2.1.5.2.1.1	SC: Pre-Production pixel detectors test schedule contingency	11Apr06	08May06	20d	72d					
1.2.2.1.7.9	T5M: Receive all FPIX wafers	11Apr06	11Apr06		116d		<u> </u>			
1.2.1.6.1.1.1.6	SC: Production detector hybridization procurement contingency task	09Jun06	07Jul06	20d	72d					
1.2.1.6.1.2.2	T2M:Release funds for production detector hybridization	10Jul06	10Jul06		72d		A			
1.2.3.6.3.10.3	SC: Cooling system design schedule contingency	04Aug06	130ct06	50d	264d					
1.2.4.1.4.7.4	SC: Production pixel module assembly/test schedule contingency	07Dec06	22Jan07	30d	166d					
1.2.1.3.1.5.3.7	SC: Production sensor schedule contingency	04Jan07	15Feb07	30d	212d					
1.2.1.3.1.6	T4M: Production sensor wafers completely delivered & tested	15Feb07	15Feb07		212d			<u> </u>		
1.2.4.3.6.2.7	SC: Pixel station assembly schedule contingency	30Aug07	110ct07	30d	72d					
1.2.4.3.6.2.8	T2M: Final pixel detector station assembly started	110ct07		Ц	72d					
1.2.1.6.1.2.7.5.4	SC: Production detector hybridizal T2M: Final pixel detector stat	ion asser	nbly start	<mark>ed </mark> d	72d					
1.2.4.4.8.2.4	SC: Pixel half-detector assembly/test schedule contingency	08Hov07	07Dec07	20d	123d					
1.2.1.6.5.3	SC: Production pixel detector testing schedule contingency task	12Dec07	14Jan08	20d	105d					
1.2.1.6.1.2.8	T4M: Receive all Production pixel detectors	01Feb08	01Feb08		72d					
1.2.4.1.4.10	T2M: Production Pixel Module Completed	11Apr08	11Apr08		103d					
1.2.4.3.7.5	SC: Pixel station test schedule contingency	14Aug08	04Sep08	15d	72d					
1.2.4.3.7.6	T4M: All pixel stations assembled & tested	04Sep08	04Sep08		72d				_	
1.2.7.2.2	T1M-6: Pixel System Tested/ Ready for Installation at C0	06May09	06May09		72d				_	A
1.2.6.4.2.19	Lk4M: Installation Need-by date for Pixel detector	17Aug09	17Aug09		0					

Risk Event	Mitigation
Major Construction Problems with Half View Production	The best strategy is to have a robust production prototype construction so that we can identify production problems before we actually enter production. A standby strategy is to have backup sites which could contribute to Half-View production once their original function is accomplished. For example, once the Straw Preparation Facility has finished, it could convert to a Half-View Assembly site.
Process to produce ASDQ chips is shutdown, by the time our budget profile allows us to place order.	We need to identify a source of funds that allows us to commit to a wafer run as early in the project as possible-while the current wafer process still exists. We could delay the packaging to later in the project timeline, when more funds become available.



Straw Level 2&3 Milestones + WBS1.6

WBS1.6	Forward Straw Tracker	Date
1.6.7.4.1	T3M-38:PO Awarded: Production ASDQ Chips *	October 10, 2005
1.6.7.4.2	T3M-39:ASDQ Procurement completed	August 3, 2006
1.6.7.4.3	T3M-40:Straw Preparation Site Functional	March 7, 2006
1.6.7.4.4	T3M-41: Half-View Production/ Assembly Sites Functional	February 7, 2007
1.6.7.4.5	T3M-42: Station 1 ready for Installation *	April 3, 2008
1.6.7.4.6	T3M-43: Station 7 ready for Installation	June 12, 2008

* Also a Level 2 Milestone

+ without Distributed Float





- Risks
 - 1. 0.25μm CMOS process disappears before we go into production

- Mitigation
 - 1. Work with multiple vendors. Keep in close contact with vendors to understand their future plans.



Key Milestones WBS 1.7 Without Distributed Float

Milestone	Date
T3M-44 Sensor accepted for full production	Jan 10, 2007
T3M-45: Production sensors received and tested	Oct 18, 2007
T3M-46: Readout IC approved for production	Aug 3, 2006
T3M-48: Production ICs Received tested and thinned	Feb 8, 2007
T3M-49: Hybrids approved for production	Nov 13, 2006
T3M-50: Hybrids complete and tested	Jan 3, 2008
T3M-51: Station support procurement complete	Oct 3, 2008
T3M-52: Ladder production 100% Complete	Jul 8, 2008
T3M-53: First FSIL station ready to be installed in C0	Aug 27, 2008
T3M-54: Last FSIL station ready to be installed in C0	Sep 15, 2008